

# Partial vs. Complete Domination: *t*-DOMINATING SET

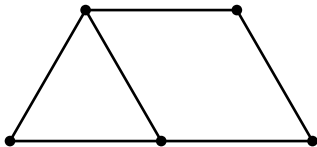
Joachim Kneis   Daniel Mölle   Peter Rossmanith

Theory Group, RWTH Aachen University

January 22, 2007

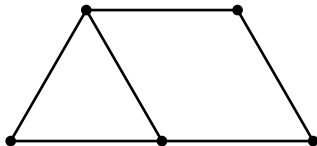
# Complete vs. Partial Solutions

VERTEX COVER (VC):



Cover all edges.

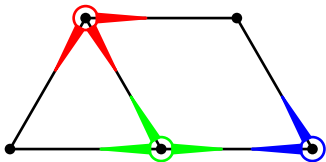
DOMINATING SET (DS):



Dominate all nodes.

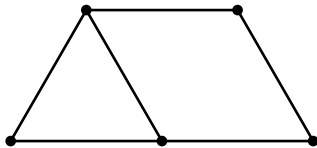
# Complete vs. Partial Solutions

VERTEX COVER (VC):



Cover all edges.

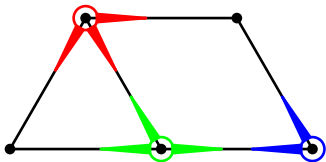
DOMINATING SET (DS):



Dominate all nodes.

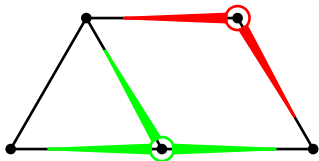
# Complete vs. Partial Solutions

VERTEX COVER (VC):



Cover all edges.

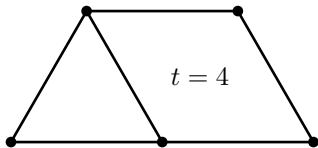
DOMINATING SET (DS):



Dominate all nodes.

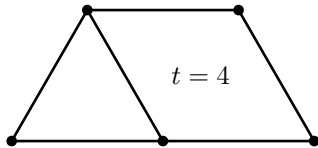
# Complete vs. Partial Solutions

$t$ -VERTEX COVER ( $t$ -VC):



Cover  $t$  edges.

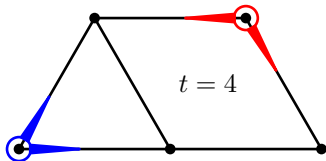
$t$ -DOMINATING SET ( $t$ -DS):



Dominate  $t$  nodes.

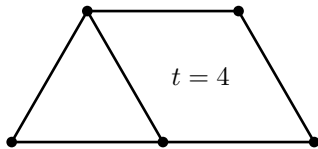
# Complete vs. Partial Solutions

$t$ -VERTEX COVER ( $t$ -VC):



Cover  $t$  edges.

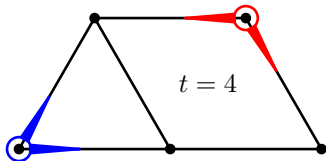
$t$ -DOMINATING SET ( $t$ -DS):



Dominate  $t$  nodes.

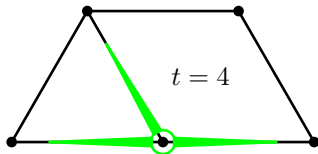
# Complete vs. Partial Solutions

$t$ -VERTEX COVER ( $t$ -VC):



Cover  $t$  edges.

$t$ -DOMINATING SET ( $t$ -DS):



Dominate  $t$  nodes.

# Parameterized Complexity

Downey and Fellows: *Parameterized Complexity*, 1999.

Flum and Grohe: *Parameterized Complexity Theory*, 2006.

Niedermeier: *Invitation to Fixed-Parameter Algorithms*, 2006.

- Analyze complexity in  $n$  and a parameter  $k$
- $L$  with parameter  $k$  is in FPT  $:\Leftrightarrow$   
 $L$  can be solved in time  $O(f(k) \cdot \text{poly}(n))$
- Hierarchy:  $\text{FPT} \subseteq \text{W}[1] \subseteq \text{W}[2] \subseteq \dots$
- Seemingly,  $L$  cannot be in FPT if it is  $\text{W}[1]$ -hard



# Parameterized Complexity

Downey and Fellows: *Parameterized Complexity*, 1999.

Flum and Grohe: *Parameterized Complexity Theory*, 2006.

Niedermeier: *Invitation to Fixed-Parameter Algorithms*, 2006.

- Analyze complexity in  $n$  and a parameter  $k$
- $L$  with parameter  $k$  is in FPT  $:\Leftrightarrow$   
 $L$  can be solved in time  $O(f(k) \cdot \text{poly}(n))$
- Hierarchy:  $\text{FPT} \subseteq \text{W}[1] \subseteq \text{W}[2] \subseteq \dots$
- Seemingly,  $L$  cannot be in FPT if it is  $\text{W}[1]$ -hard

# Parameterized Complexity

Downey and Fellows: *Parameterized Complexity*, 1999.

Flum and Grohe: *Parameterized Complexity Theory*, 2006.

Niedermeier: *Invitation to Fixed-Parameter Algorithms*, 2006.

- Analyze complexity in  $n$  and a parameter  $k$
- $L$  with parameter  $k$  is in FPT  $:\Leftrightarrow$   
 $L$  can be solved in time  $O(f(k) \cdot \text{poly}(n))$
- Hierarchy:  $\text{FPT} \subseteq \text{W}[1] \subseteq \text{W}[2] \subseteq \dots$
- Seemingly,  $L$  cannot be in FPT if it is  $\text{W}[1]$ -hard

# Parameterized Complexity

Downey and Fellows: *Parameterized Complexity*, 1999.

Flum and Grohe: *Parameterized Complexity Theory*, 2006.

Niedermeier: *Invitation to Fixed-Parameter Algorithms*, 2006.

- Analyze complexity in  $n$  and a parameter  $k$
- $L$  with parameter  $k$  is in FPT  $:\Leftrightarrow$   
 $L$  can be solved in time  $O(f(k) \cdot \text{poly}(n))$
- Hierarchy:  $\text{FPT} \subseteq \text{W}[1] \subseteq \text{W}[2] \subseteq \dots$
- Seemingly,  $L$  cannot be in FPT if it is W[1]-hard

# Parameterized Complexity

Downey and Fellows: *Parameterized Complexity*, 1999.

Flum and Grohe: *Parameterized Complexity Theory*, 2006.

Niedermeier: *Invitation to Fixed-Parameter Algorithms*, 2006.

- Analyze complexity in  $n$  and a parameter  $k$
- $L$  with parameter  $k$  is in FPT  $:\Leftrightarrow$   
 $L$  can be solved in time  $O(f(k) \cdot \text{poly}(n))$
- Hierarchy:  $\text{FPT} \subseteq \text{W}[1] \subseteq \text{W}[2] \subseteq \dots$
- Seemingly,  $L$  cannot be in FPT if it is W[1]-hard

# Complete vs. Partial Solutions

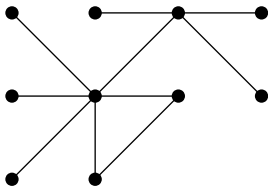
Problem	Parameter	Best result	Reference
VC	$k$	$O(1.2738^k + kn)$	Chen et al.
$t$ -VC	$k$	W[1]-hard	Guo et al.
$t$ -VC	$t$	$O(2.0911^t n(n+m)k)$	ISAAC'06
DS	$k$	W[2]-complete	DF99
$t$ -DS	$k$	W[2]-hard	(obvious)
$t$ -DS	$t$	$O((4 + \varepsilon)^t \text{poly}(n))$	(today)

# Algorithmics for $t$ -Vertex Cover

Method	Result	Reference
Color-Coding	$5.4366^t \cdot \text{poly}(n)$	M. Bläser
Random Separation	$4.0000^t \cdot \text{poly}(n)$	Cai et al.
Randomized Branching	$2.0911^t \cdot \text{poly}(n)$	ISAAC'06

## Divide-and-Color

LONGEST PATH: Does  $G = (V, E)$  contain a  $k$ -node path?

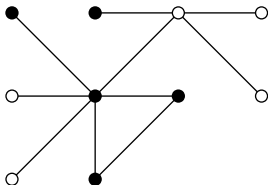


- 1 Randomly color  $G$  in black and white.
- 2 Recursively check for a black  $\lceil k/2 \rceil$ -node path and a white  $\lfloor k/2 \rfloor$ -node path that combine to form a  $k$ -node path in  $G$ .

→ Randomized  $O(4^k \cdot \text{poly}(n))$  algorithm [WG 2006]

## Divide-and-Color

LONGEST PATH: Does  $G = (V, E)$  contain a  $k$ -node path?



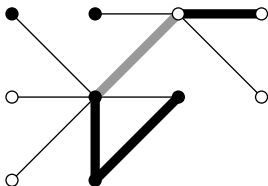
- 1 Randomly color  $G$  in black and white.
- 2 Recursively check for a black  $\lceil k/2 \rceil$ -node path and a white  $\lfloor k/2 \rfloor$ -node path that combine to form a  $k$ -node path in  $G$ .

→ Randomized  $O(4^k \cdot \text{poly}(n))$  algorithm [WG 2006]



## Divide-and-Color

LONGEST PATH: Does  $G = (V, E)$  contain a  $k$ -node path?

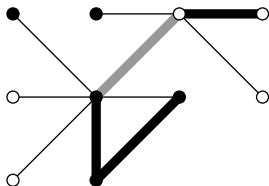


- 1 Randomly color  $G$  in black and white.
- 2 Recursively check for a black  $\lceil k/2 \rceil$ -node path and a white  $\lfloor k/2 \rfloor$ -node path that combine to form a  $k$ -node path in  $G$ .

→ Randomized  $O(4^k \cdot \text{poly}(n))$  algorithm [WG 2006]

## Divide-and-Color

LONGEST PATH: Does  $G = (V, E)$  contain a  $k$ -node path?



- 1 Randomly color  $G$  in black and white.
- 2 Recursively check for a black  $\lceil k/2 \rceil$ -node path and a white  $\lfloor k/2 \rfloor$ -node path that combine to form a  $k$ -node path in  $G$ .

→ Randomized  $O(4^k \cdot \text{poly}(n))$  algorithm [WG 2006]

# Divide-and-Color

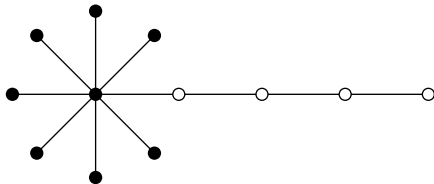
Applied to  $t$ -DOMINATING SET:

- 1 Randomly color  $G$  in black and white.
- 2 Recursively check for a black  $\lceil t/2 \rceil$ -DS and a white  $\lfloor t/2 \rfloor$ -DS whose combined size is  $\leq k$ .

→ Randomized  $O(4^t \cdot \text{poly}(n))$  algorithm?

# Unbalanced Solutions

Let  $k = 2$ ,  $t = 10$ :



Every  $t$ -DS of size  $k$  is *unbalanced*.

# Unbalanced Solutions

What if all minimum solutions are unbalanced?

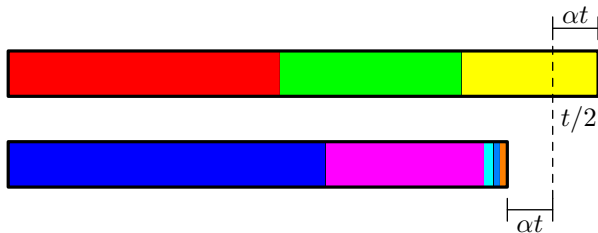


- PARTITION: Imbalance requires large numbers
- $t$ -DS: Imbalance requires high-degree nodes

→ A small fraction of a solution yields a  $t/2$ -DS

# Unbalanced Solutions

We define  $\alpha$ -balance:



Lemma:  $\neg \exists \alpha$ -balanced solution  $\Rightarrow \exists t/2$ -DS of size  $\beta := \lceil \frac{1}{2\alpha} \rceil$

## Towards an Algorithm

TDS( $G, t$ ):

**if**  $\exists$  small solution  $D$  **then return**  $D$ ; **fi**;

**if**  $|V| = \emptyset$  **then return**  $\infty$ ; **fi**

$k_{opt} := \infty$ ;

**for**  $4 \cdot 2^t$  **times do**

**color**  $G$ ;

$k_{opt} \leftarrow$   $\langle$ Handle the unbalanced case $\rangle$ ;

$k_{opt} \leftarrow$   $\langle$ Handle the balanced case $\rangle$ ;

**endfor**;

**return**  $k_{opt}$ ;

# Correctness

## Lemma

$TDS(G, t)$  returns the size of a minimum  $t$ -DS with prob.  $\geq \frac{1}{2}$ .

### Unbalanced case:

- Good coloring:  $2^{-t}$
- Recursive call:  $\frac{1}{2}$
- Total failure probability:

$$\left(1 - 2^{-t} \cdot \frac{1}{2}\right)^{4 \cdot 2^t} \leq e^{-2}$$

### Balanced case:

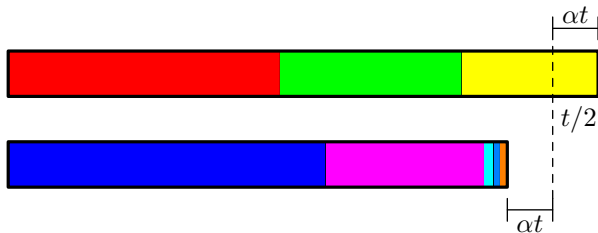
- Good coloring:  $2^{-t}$
- Recursive call:  $\frac{1}{2} \cdot \frac{1}{2}$
- Total failure probability:

$$\left(1 - 2^{-t} \cdot \frac{1}{4}\right)^{4 \cdot 2^t} \leq e^{-1}$$



# Runtime Bound

Recall  $\alpha$ -balance:



## Lemma

$TDS(G, t)$  performs  $\leq 4^{(1+\alpha)t} \cdot t^6$  recursive calls.

# Main Result

## Theorem

*Let  $0 < \alpha \leq 1/25$ .  $t$ -DOMINATING SET can be solved with exponential small error probability in time*

$$O((4 + 6\alpha)^t \cdot t^6 \cdot n^{\lfloor \frac{1}{2\alpha} \rfloor + 1}).$$

Derandomized:  $O((16 + \varepsilon)^t \text{poly}(n))$