Estimates of Data Complexity in Neural Network Learning

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Learning = optimization problem



hypothesis set of network I/O functions

functional defined by data

minimize Φ over M

 $span_n G =$ linear combinations of nfunctions corresponding to the type of computational units

expected error functional \mathcal{E}_{ρ} empirical error functional \mathcal{E}_z

Functional defined by a sample of data

 $z = \{(u_i, v_i) : i = 1, \dots, m\} \subseteq \mathbb{R}^d imes \mathbb{R}$ sample of data

Empirical error functional

$$\boldsymbol{\mathcal{E}}_{\boldsymbol{z}}(f) = \frac{1}{m} \sum_{i=1}^{m} (f(\boldsymbol{u}_i) - \boldsymbol{v}_i)^2$$



Minimization of empirical error functional = the least square method Gauss 1809, Legendre 1806

Functional defined by a probability measure

ho = nondegenerate (no nonempty open set has measure zero) probability measure on $Z = X \times Y$ ho(Z) = 1 $X \subset \mathbb{R}^d$ compact $Y \subset \mathbb{R}$ bounded

Expected error functional

 $\mathcal{E}_{\rho}(f) = \int_{X \times Y} (f(u) - v)^2 d\rho$

The least square method: statistical inference, pattern recognition, function approximation, curve or surface fitting, etc.

the best fitting function was searched for in LINEAR hypothesis spaces

 \Rightarrow limitations on applications to high-dimensional data!

CURSE OF DIMENSIONALITY

the dimension of a linear space needed for approximation of a function of d variables within accuracy ε is $\mathcal{O}\left(\left(\frac{1}{\varepsilon}\right)^d\right)$

 \Rightarrow complexity of LINEAR models grows EXPONENTIALLY with the data dimension d

Hypothesis sets in neurocomputing

 $\operatorname{span}_{\mathbf{n}} G = \{\sum_{i=1}^{\mathbf{n}} \omega_i g_i \, | \, \omega_i \in \mathbb{R}, g_i \in G\}$

= set of functions computable by a network with one linear output and n hidden units computing functions from the set GNONLINEAR and NONCONVEX

Computational units: Heaviside perceptrons



$$\begin{split} H_d(X) &= \{ \vartheta(e \cdot x + b) : X \to \mathbb{R} \mid e \in S^{d-1}, b \in \mathbb{R} \} \\ \text{set of characteristic functions of half-spaces of } X \subseteq \mathbb{R}^d \end{split}$$

 $\operatorname{span}_{n} H_{d}(X) = \operatorname{set}$ of functions on $X \subset \mathbb{R}^{d}$ computable by neural networks with n Heaviside perceptrons and one linear output

Heaviside perceptrons



compute functions of the form $\vartheta(\mathbf{e} \cdot x + \mathbf{b})$

= characteristic functions of half-spaces

Optimal solution

Global minimum of expected error

Regression function

$$f_{
ho}(x) = \int_Y y \, d
ho(y|x)$$

 $\rho(y|x) = \text{conditional (w.r.t. } x) \text{ probability measure on } Y$ $\rho_X = \text{marginal probability measure on } X \quad (\forall S \subseteq X) \quad \rho_X(S) = \rho(\pi_X^{-1}(S)), \quad \pi_X : X \times Y \to X \text{ projection})$

$$\min_{f \in \mathcal{L}^2_{\rho_X}} \mathcal{E}_{\rho}(f) = \mathcal{E}_{\rho}(f_{\rho})$$

the regression function f_{ρ} is global minimizer of \mathcal{E}_{ρ} over $\mathcal{L}_{\rho_X}^2$

Optimal solution

Existence of the global minimum of empirical error over a set of functions computable by perceptron networks

Ito (92) \forall sample of data z of size m \exists interpolating function f^o computable by a network with m perceptrons $f^o \in \operatorname{span}_m H_d$

$$\min_{f \in \operatorname{span}_{m} H_{d}} \mathcal{E}_{z}(f) = \mathcal{E}_{z}(f^{o}) = 0$$

similar results for RBF and kernel units

Approximate minimization

optimal solutions f^o and the regression function f_ρ may not be computable by networks with a reasonably small number of hidden units

BUT they can be approximated by suboptimal solutions = minima over $\operatorname{span}_n G$ with $n \ll m$ number of units

approximation of the problems $(\operatorname{span}_m G, \mathcal{E}_z)$ and $(\operatorname{span}_m G, \mathcal{E}_\rho)$

by a sequence of problems

 $\{(\operatorname{span}_{\boldsymbol{n}} G, \mathcal{E}_{\boldsymbol{z}}) | \, \boldsymbol{n} = 1, \dots, \boldsymbol{m}\} \text{ and } \{(\operatorname{span}_{\boldsymbol{n}} G, \mathcal{E}_{\boldsymbol{\rho}}) | \, \boldsymbol{n} = 1, \dots, \boldsymbol{m}\}$

? speed of convergence ?

 $\inf_{f \in \operatorname{span}_{\boldsymbol{n}} G} \mathcal{E}_{\boldsymbol{z}}(f) \to 0 \quad \text{and} \quad \inf_{f \in \operatorname{span}_{\boldsymbol{n}} G} \mathcal{E}_{\boldsymbol{\rho}}(f) \to \mathcal{E}_{\boldsymbol{\rho}}(f_{\boldsymbol{\rho}})$

Tools from approximation theory

minimization of expected error \mathcal{E}_{ρ} is equivalent to minimization of the $\mathcal{L}_{\rho_X}^2$ -distance from the regression function f_{ρ}

minimization of empirical error \mathcal{E}_z is equivalent to minimization of the l^2 -distance from f_z

 \Rightarrow we can use tools from approximation theory to estimate speed of convergence of infima (minima) of error functionals over span_nG with *n* increasing Rates of convergence of infima of expected error functional over networks with n units

$$\inf_{f \in \operatorname{span}_{\boldsymbol{n}} G} \mathcal{E}_{\boldsymbol{\rho}}(f) - \mathcal{E}_{\boldsymbol{\rho}}(f_{\boldsymbol{\rho}}) \leq \frac{\|f_{\boldsymbol{\rho}}\|_{G}^{2}}{n}$$

 $||f_{\rho}||_{G} =$ norm tailored to G variation with respect to G

value of the variation norm at f_{ρ} = measure of complexity ("smoothness") of data wrt the class of networks with units computing functions from G

Rates of convergence of minima of empirical error functional over networks with n units

for every h interpolating the sample z

$$\inf_{f \in \operatorname{span}_{\boldsymbol{n}} \boldsymbol{G}} \mathcal{E}_{\boldsymbol{z}}(f) \leq \frac{\|\boldsymbol{h}\|_{\boldsymbol{G}}^2}{\boldsymbol{n}}$$

the smallest value of the variational norm of

- a function interpolating z
- = measure of complexity ("smoothness") of data wrt the class
- of networks with units computing functions from G

Comparison with linear approximation

number of hidden units = network complexity needed for approximation within ε grows as

$$\left(\frac{\|f_{\rho}\|_{G}}{\varepsilon}\right)^{2} \quad \text{or} \quad \left(\frac{\|h\|_{G}}{\varepsilon}\right)^{2}$$

in contrast to $\mathcal{O}\left(\left(\frac{1}{\varepsilon}\right)^{d}\right)$ in linear approximation

? dependence of variational norm on dimensionality d= number of variables of functions in G = number of network inputs

Variation with respect to half-spaces

 H_d -variation = Minkowski functional of the closed convex symmetric hull of H_d

$$\|f\|_{H_d} = \inf\{b > 0: \frac{f}{b} \in cl \ conv(H_d \cup -H_d)\}$$

ng.

function

d = 1generalization of total variation $T(f) = \int |f'| \qquad d = 1$ \approx sum of "heights of steps"



Heaviside activation

Smooth functions have small variations wrt half-paces

Kainen, Kůrková, Vogt (2005)



$$\begin{split} \|f\|_{d,1,\infty} \text{ is much smaller than } \|f\|_{d,1} &= \sum_{|\alpha| \leq d} \|D^{\alpha}f\|_{\mathcal{L}_1(\mathbb{R}^d)} \\ \|f\|_{d,1,\infty} \text{ is maximum of partial derivatives,} \\ \text{while } \|f\|_{d,1} \text{ is sum of } 2^d \text{ partial derivatives} \end{split}$$

$$D^{\alpha}f = \frac{\partial^{\alpha_1}}{\partial x_1} \dots \frac{\partial^{\alpha_d}}{\partial x_d}f \qquad |\alpha| = \sum_{i=1}^d \alpha_i$$

Integral representation as a perceptron network with a continuum of hidden units

Kůrková Kainen, Kreinovich (1997) Kainen, Kůrková, Vogt (2005) $\forall d \text{ odd } \forall f : \mathbb{R}^d \to \mathbb{R}$ sufficiently quickly vanishing at infinity

$$\begin{split} f(x) &= \int\limits_{S^{d-1}} \int\limits_{\mathbb{R}} w_f(e,b) \vartheta(e \cdot x + b) dedb \\ \omega_f(e,b) &= a_d \int\limits_{H_{e,b}} (D_e^d f)(y) dy \qquad a_d = \frac{(-1)^{\frac{d-1}{2}}}{2} (2\pi)^{1-d} \end{split}$$

 $\omega_f(e,b)$ is orthogonal flow of order d through hyperplane $H_{e,b}=\{x\in\mathbb{R}^d,e\cdot x+b=0\}$ a_d is exponentially decreasing

$$\|f\|_{H_d,\sup} \leq \int\limits_{S^{d-1}} \int\limits_{\mathbb{R}} |\omega_f(e,b)| dedb = \|\omega_f\|_{\mathcal{L}_1(S^{d-1}\times\mathbb{R})}$$

Fast rates of approximate minimization of empirical error over perceptron networks

If a sample of data z determining the empirical error \mathcal{E}_z can be interpolated by a function hwith the Sobolev seminorm $||h||_{d,1,\infty} \leq \sqrt{d} 2^{d/2}$, then

$$\min_{f \in \operatorname{span}_{\boldsymbol{n}} H_d} \mathcal{E}_{\boldsymbol{z}}(f) \leq \frac{1}{\boldsymbol{n}}$$

Fast rates $\frac{1}{n m}$ of approximate minimization of empirical error \mathcal{E}_z over Heaviside perceptron networks are guaranteed for samples of data z that can be interpolated by functions with quite large Sobolev seminorms (bounded from above by $\sqrt{d} 2^{d/2}$)

Example: Samples chosen from the Gaussian function

z sample chosen from the Gaussian function

$$\begin{split} \gamma(x) &= e^{-\|x\|^2} : \mathbb{R}^d \to \mathbb{R} \\ \|\gamma\|_{H_d} \leq 2d \quad \Rightarrow \quad \min_{f \in span_n H_d} \mathcal{E}_z(f) \leq \frac{4d^2}{n} \end{split}$$

relationship between two types of geometrically opposite units: perceptrons and radial-basis functions

Samples of data that cannot be interpolated by sufficiently smooth functions

every Boolean function $f : \{0,1\}^d \rightarrow \mathbb{R}$ determines a sample $z = \{(u_i, v_i) | i = 1, \dots, 2^d\}$ defined as $\{u_1, \dots, u_{2^d}\} = \{0,1\}^d$ and $v_i = f(u_i)$

for every function $h:X\to \mathbb{R}$ interpolating data \boldsymbol{z}

 $\|f\|_{H_d(\{0,1\}^d)} \le \|h\|_{H_d(X)}$

 \Rightarrow a lower bound on variation wrt half-spaces of the Boolean function f is also a lower bound on variation of every function hinterpolating the data z defined by f

 \Rightarrow we can use lower bounds on variations of Boolean functions

Functions with variations wrt half-spaces depending on the number of variables *d* exponentially

 ${\rm card}\, H_d(\{0,1\}^d) < 2^{d^2}$

BUT

$$\dim_{\varepsilon} 2^d$$
 is large $\dim_{\varepsilon} 2^d = e^{\frac{2^d \varepsilon^2}{2}}$

 \Rightarrow there exist functions with variations wrt half-spaces depending on the number of variables d exponentially

Example: inner product modulo 2 has $H_d(\{0,1\}^d)\text{-variation}$ at least $\mathcal{O}(2^{d/6})$

Geometric characterization of *G*-variation

Kůrková, Savický, Hlaváčková 98

 $\|f\|_{\boldsymbol{G}} \geq \frac{\|f\|^2}{\sup_{\boldsymbol{g} \in \boldsymbol{G}} |f \cdot \boldsymbol{g}|}$



functions that are "almost orthogonal" to G have large G-variation

Hahn-Banach Theorem

Functions with large variation and covering numbers

 $S_1 = S_1(\|\cdot\|)$ unit sphere in a Hilbert space $(X, \|\cdot\|)$ μ_X pseudometrics on S_1 $\mu_X (f, g) = \arccos |f \cdot g|$

minimum of two angles: between f and g and between f and -g

 $\alpha > 0$ $\mathcal{N}_{\alpha}(S_1)$ α -covering number of S_1 with respect to μ_X (smallest number of balls of radius α covering S_1)

if card $G < \mathcal{N}_{\alpha}(S_1) \Rightarrow$

 S_1 contains a function with G-variation greater than $\frac{1}{\cos \alpha}$

Set of characteristic functions of Boolean half-spaces is small wrt covering numbers of S^{2^d-1}

samples of data z represented by Boolean functions

 $\{f: \{0,1\}^d \to \mathbb{R}\} = \mathbb{R}^{2^d}$

hypothesis set = set of characteristic functions of half-spaces of the Boolean cube $H_d(\{0,1\}^d)$

 $\operatorname{card} H_d(\{0,1\}^d)$ is small

Shläfli card $H_d(\{0,1\}^d) = 2^{d^2 - d \log_2 d + \mathcal{O}(d)} < 2^{d^2}$ as $d \to \infty$

Quasiorthogonal dimension of Euclidean spaces

$$\begin{split} \varepsilon &> 0 \qquad u, v \in \mathbb{R}^m \\ (u, v) \text{ are } \varepsilon \text{-quasiorthogonal if} \\ |u \cdot v| &\leq \varepsilon \|u\| \, \|v\| \end{split}$$





 $\dim_{\boldsymbol{\varepsilon}} m$

= maximal number of pairwise ε -quasiorthogonal vectors

 $\dim_{\varepsilon} m$ is large $\Rightarrow \mathcal{N}_{\arccos \varepsilon}(S^{m-1})$ is large

 $G \subseteq S^{m-1} \subseteq \mathbb{R}^m$ $\operatorname{card} G \leq \dim_{\varepsilon} m \Rightarrow \exists f \in S^{m-1}$ $\|f\|_G \geq \frac{1}{\varepsilon}$

Kainen, Kůrková 93 $\dim_{\varepsilon} m \ge e^{\frac{m\varepsilon^2}{2}}$ as $\varepsilon \to 0$ and $m \to \infty$