

Factorization for Component-Interaction Automata

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Component-Based Software Development

- autonomous (third-party) components
- hierarchical composition
- correctness issues

Component-Interaction Automata

- automata-based formalism
- various kinds of component assembly
- captures interaction properties



Factorization Problem

- dual to composition
- filling a “gap” in a system



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Formally:

- let \parallel be a **composition** operation
- let \simeq be a **conformity** relation (equivalence, refinement, ...)
- given S, M , find X such that $X \parallel M \simeq S$

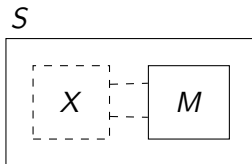


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Component-Interaction Automata

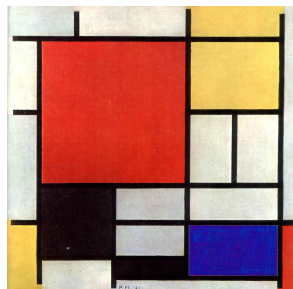
- labelled transition systems
- equipped with **ports** and **actions**

Component-Interaction Automata

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- equipped with **ports** and **actions**
- labels are triples (*from*, *action*, *to*)
 - input: $(-, a, 1)$
 - output: $(1, a, -)$
 - internal: $(1, a, 1)$, $(1, a, 2)$

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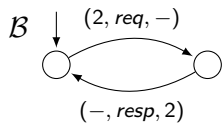
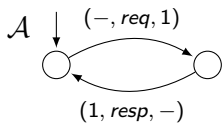
Composition $\otimes^{\mathcal{F}}$

- two CI automata with disjoint ports
- complementary labels may be combined

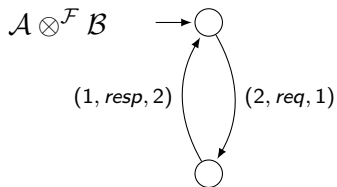
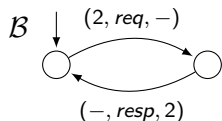
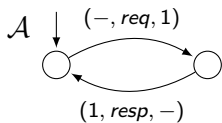
$$(1, a, -) + (-, a, 2) \rightarrow (1, a, 2)$$

- composition parameter \mathcal{F} – which labels ought to be combined and/or left open

Example

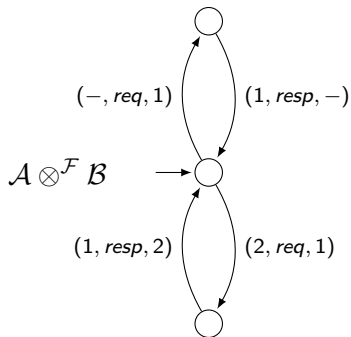
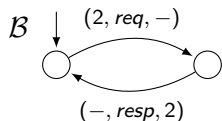
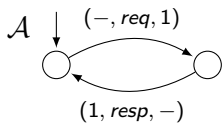


Example



$$\mathcal{F} = \{(2, req, 1), (1, resp, 2)\}$$

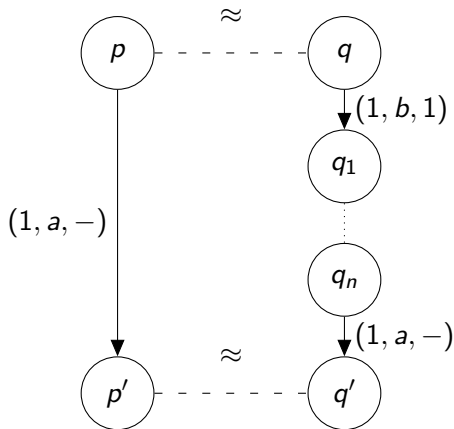
Example



$$\mathcal{F} = \{(2, req, 1), (1, resp, 2), (-, req, 1), (1, resp, -)\}$$

Weak Bisimulation \approx

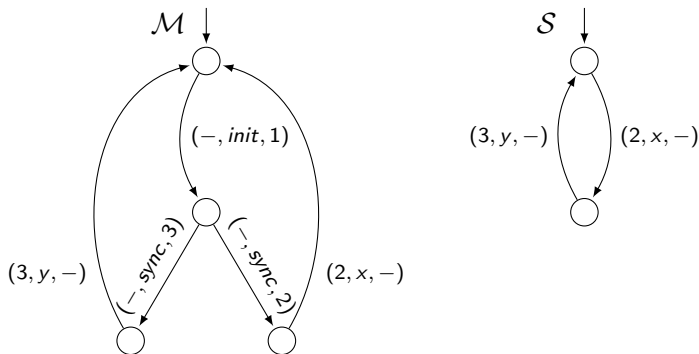
- observational equivalence
- ignore (in certain sense) internal transitions



Our Problem

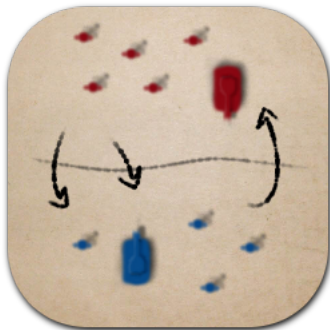
Factorization Problem for Component-Interaction Automata

Given two CI automata \mathcal{S} , \mathcal{M} , find a parameter \mathcal{F} and a CI automaton \mathcal{X} such that $\mathcal{X} \otimes^{\mathcal{F}} \mathcal{M} \approx \mathcal{S}$.



The “Battle Plan”: Reduction to Similar Problem

- Qin, H., Lewis, P.: Factorization of finite state machines under observational equivalence. In: CONCUR 90. LNCS, vol. 458.
- finite automata with
 - τ actions
 - handshake composition a with \bar{a}
 - weak bisimulation
- constraints on S
 - deterministic
 - without τ
- the method
 - transform \mathcal{S}, \mathcal{M} into FSMs
 - solve the FSM factorization
 - transform the result back into a CI automaton



Transformations $f, g_{\mathcal{F}} : \text{CI} \rightarrow \text{FSM}$

- the goal: $\mathcal{A} \otimes^{\mathcal{F}} \mathcal{B} \approx \mathcal{C}$ if and only if $g_{\mathcal{F}}(\mathcal{A}) \parallel g_{\mathcal{F}}(\mathcal{B}) \approx f(\mathcal{C})$
- $g_{\mathcal{F}}$ should be invertible

Transformation f

- retain the structure
- actions of the FSM are labels of the original CI automaton

Transformation $g_{\mathcal{F}}$

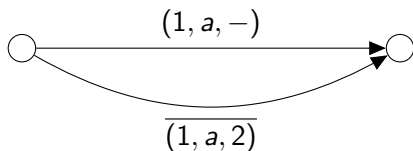
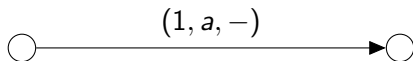
- parametrized with a set of labels \mathcal{F}
- external labels allowed by \mathcal{F} retained
- external labels that can be combined are changed and possibly multiplied

Transformation $g_{\mathcal{F}}$ – Example

- let $\mathcal{F} = \{(1, a, -), (1, a, 2), (3, b, 1), (4, b, 1)\}$

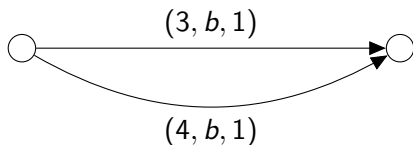
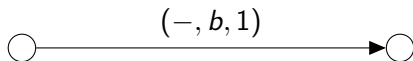
Transformation $g_{\mathcal{F}}$ – Example

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- let $\mathcal{F} = \{(1, a, -), (1, a, 2), (3, b, 1), (4, b, 1)\}$



Ensuring Invertibility of $g_{\mathcal{F}}$

- \mathcal{F} has to be label injective
- $(r, a, x), (r, a, y) \in \mathcal{F} \implies x = y$ where r is a port of \mathcal{X}

Ensuring Completeness of The Reduction

- \mathcal{F} has to be complete wrt \mathcal{M}
- for every $(m, a, -)$ of \mathcal{M} there has to some $(m, a, z) \in \mathcal{F}$

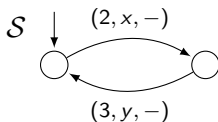
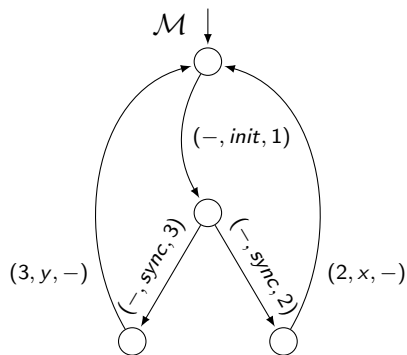
Finding the Right \mathcal{F}

- mirror the ports of \mathcal{M} : $r \rightarrow r'$
- set \mathcal{F} contains all labels of S plus (r, a, r') for every $(r, a, -)$ of \mathcal{M}

The Algorithm

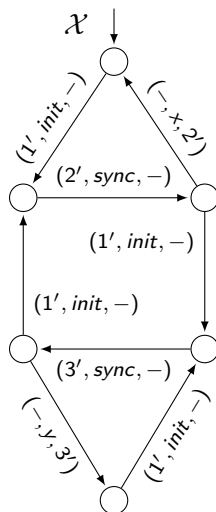
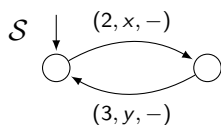
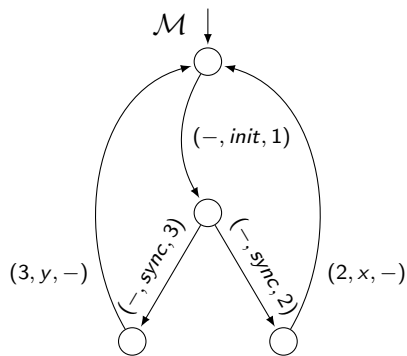
- input:** CI automata \mathcal{M} and \mathcal{S} such that \mathcal{S} is deterministic and $Reach(\mathcal{S})$ contains no internal labels.
1. Let $\mathcal{F} = Reach(\mathcal{S}) \cup \{(r, a, r') \mid (r, a, -) \in Reach(\mathcal{M})\} \cup \{(s', a, s) \mid (-, a, s) \in Reach(\mathcal{M})\}$
 2. Transform \mathcal{M} into $g_{\mathcal{F}}(\mathcal{M})$ and \mathcal{S} into $f(\mathcal{S})$.
 3. Solve the factorization problem for FSM $g_{\mathcal{F}}(\mathcal{M})$ and $f(\mathcal{S})$ using the algorithm of Qin and Lewis.
(If no solution exists, claim that no solution for the original problem exists.)
 4. Produce a CI automaton \mathcal{X} such that $g_{\mathcal{F}}(\mathcal{X})$ is the solution obtained in previous step.
 5. Output \mathcal{F} , \mathcal{X} as the solution of the original problem.

Example Solution



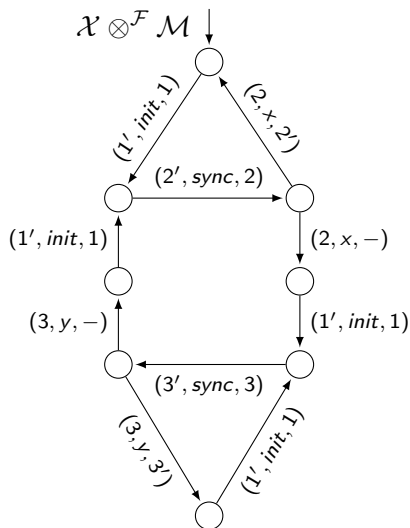
$\{(2, x, -), (3, y, -), (2, x, 2'), (3, y, 3'), (1', init, 1), (2', sync, 2), (3', sync, 3)\}$

Example Solution

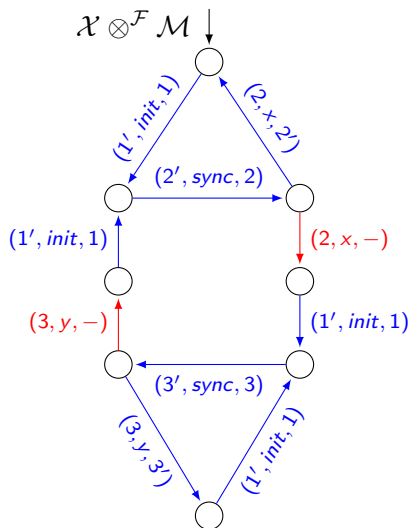


$\{(2, x, -), (3, y, -), (2, x, 2'), (3, y, 3'), (1', \text{init}, 1), (2', \text{sync}, 2), (3', \text{sync}, 3)\}$

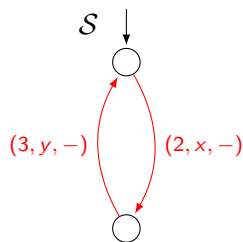
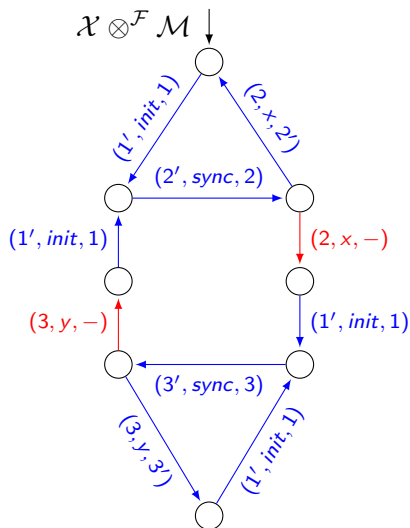
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Component-Interaction Automata

- modelling component-based systems
- flexible (parametrized) composition

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Our Solution

- reduction to FSMs, solved by Qin and Lewis (CONCUR 1990)
- requires deterministic \mathcal{S} with no internal transitions

Future Work

- port minimization
- general description of all solutions (modal transition system?)

